# Progress Report for the Smart Pet Feeder Monday March 31, 2008

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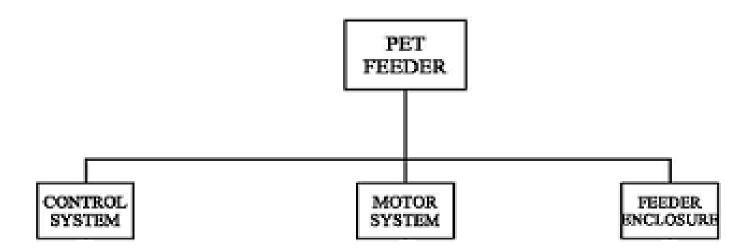
### Introduction



- Automated pet feeder that:
  - Reliably provides food to a pet at the time the owner wishes
  - Keeps the pet from reaching the food stored for later feedings
  - Does not allow a "forbidden pet" to eat from a given feeder

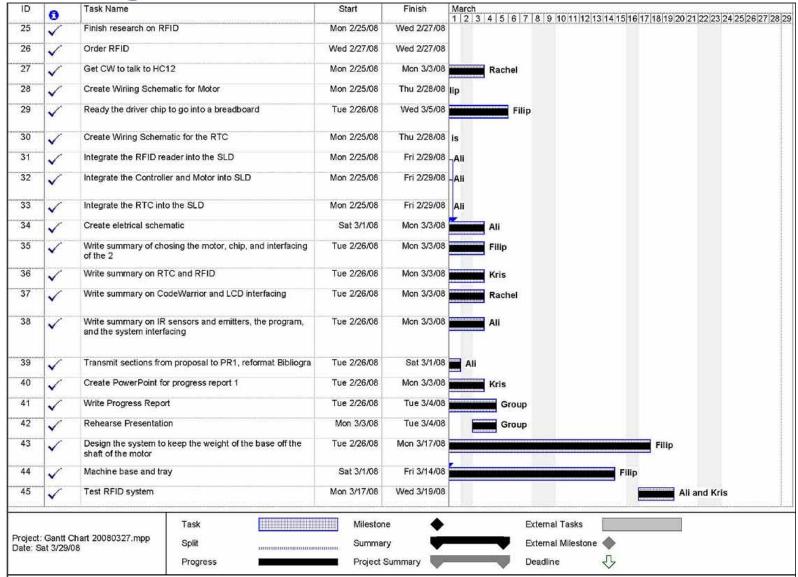
### Introduction



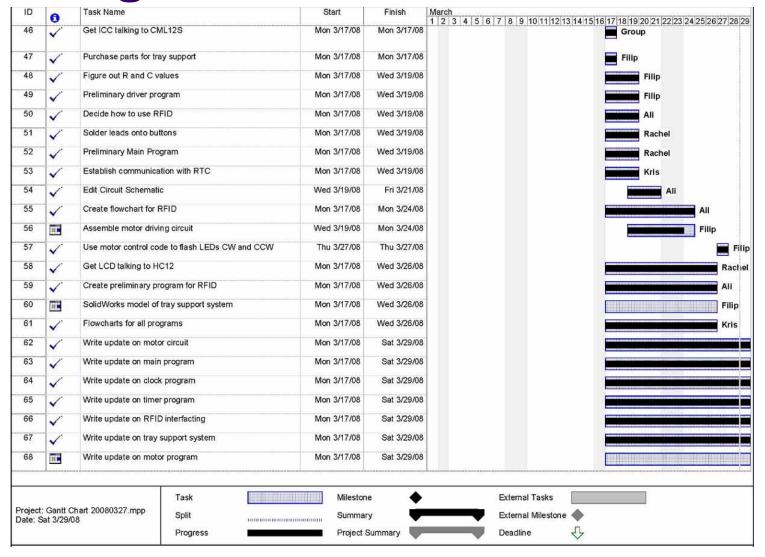


- Programming has begun
- Communication with LCD
- New IDE
- Testing of RFID
- Communication with RTC
- New parts have been machined

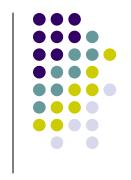




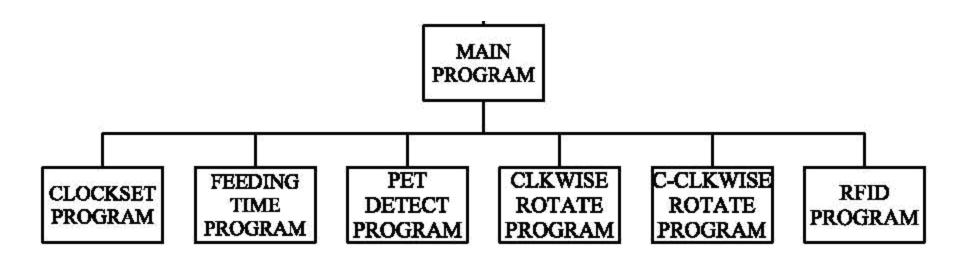




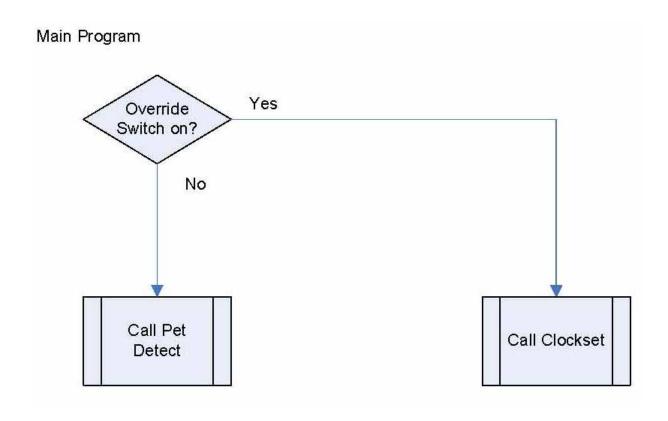




Six main subprograms of the main program:





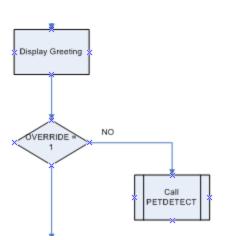


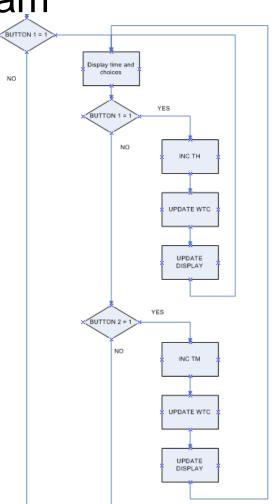


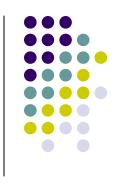
- RTC chip
  - Now communicating with it
  - Understand how the Watchdog Alarm functions
  - Input the time but it is not updating correctly

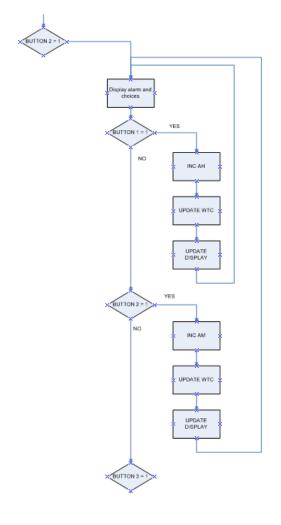


Clockset program





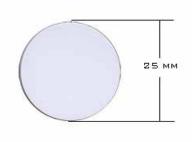


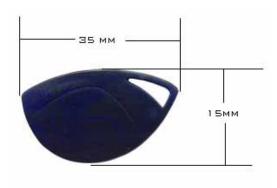


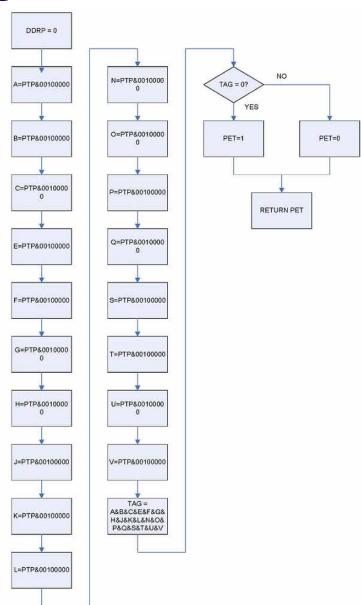
- RFID Reader/Tags
  - Received
  - Tested for range and operation
  - Found that the logic state of the SOUT pin does not change, but a unique ID number is sent when

the tag is sensed

#### •RFID Subprogram









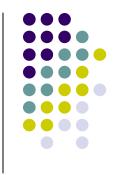


- LCD
  - Now talking to LCD
  - Have a working program
  - Program we had acquired from Axiom was not compiling
  - We realized it was not complete

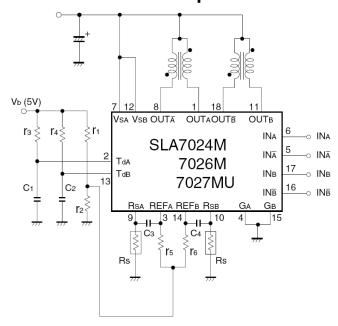


- IDE
  - Chosen a new one
    - Original IDE, "Embedded GNU", was requiring administrative rights
    - ImageCraft ICCV7
  - Communicating and compiling
    - Until recently, we believed that the programs were not downloading, but it turned out that it was



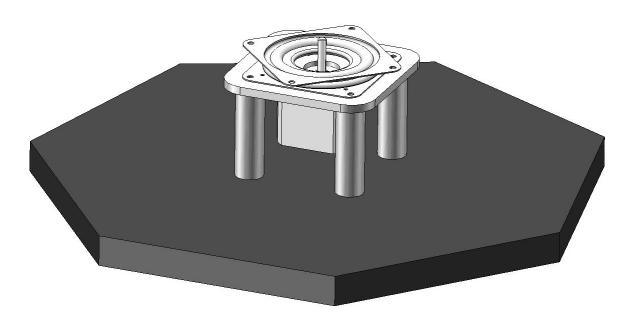


- Stepper motor
  - Received
  - Driver circuit design is complete
    - Resistor and capacitor values have been determined

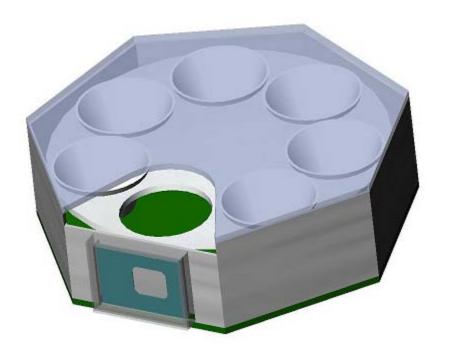


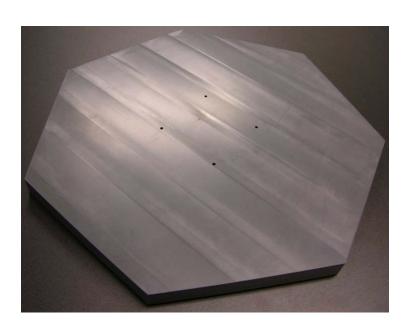
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\begin{array}{lll} \text{F1} & : 510\Omega \\ \text{F2} & : 100\Omega \text{ (VR)} \\ \text{F3} & : 47k\Omega \\ \text{F4} & : 47k\Omega \\ \text{F5} & : 2.4k\Omega \\ \text{F6} & : 2.4k\Omega \\ \text{C1} & : 470pF \\ \text{C2} & : 470pF \\ \text{C3} & : 2200pF \\ \text{C4} & : 2200pF \\ \text{C4} & : 2200pF \\ \text{Rs} & : 1\Omega \text{ typ (7024M)} \\ \text{($^{1$ to $2W)}$} & 0.68\Omega \text{ typ (7027MU)} \\ & 1.8\Omega \text{ typ (7027MU)} \end{array}
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- Support System
  - All elements machined
  - Assembly is all that is left



- Feeder enclosure
  - Base machined
    - PVC



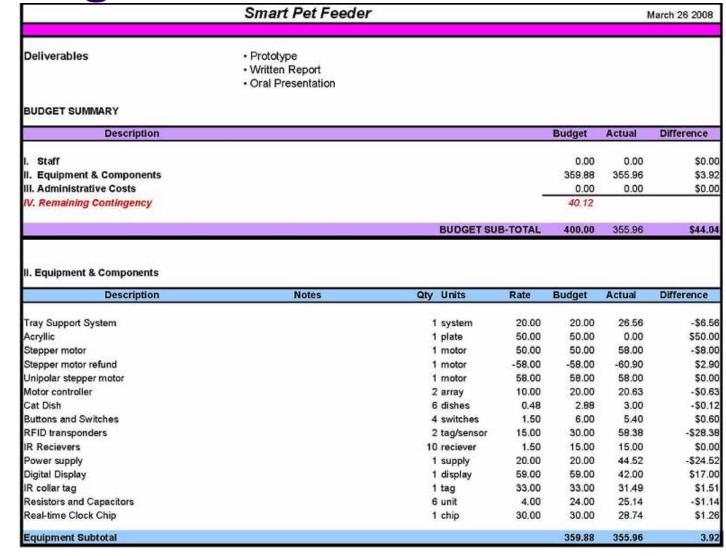


### **Problem Areas**



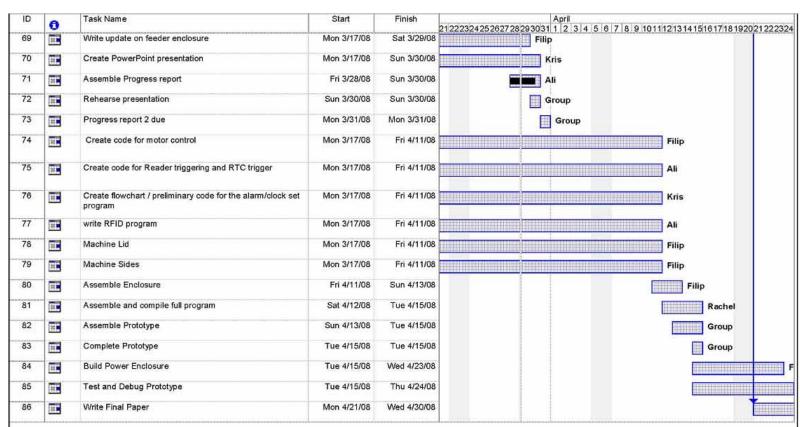
- LCD
  - Program wasn't compiling
- RTC Chip
  - Input the time but it is not updating correctly
- IDE
  - Original IDE, "Embedded GNU", was requiring administrative rights
- Downloading program
  - Board was not downloading programs

# **Budget**





### Schedule Status





Project: Gantt Chart 20080327.mpp Date: Sat 3/29/08

Task Split Progress Milestone Summary **Project Summary** 



External Tasks External Milestone Deadline

# **Bibliography**



- RFID Reader Module (#28140)." Parallax, Inc. Rocklin: 2005.
- "DS1286 Watchdog Timekeeper." <u>Jameco.com</u>. 03 Mar. 2008. < http://www.jameco.com/webapp/wcs/stores/servlet/ProductDisplay?langId=-1&storeId=10001&catalogId=10001&productId=1334 44>
- "1.8° Size 17 Super Torque Motor." Lin Engineering. Santa Clara.
- "SLA7024M, SLA7026M, and SMA7029M High-Current PWM, Unipolar Stepper." Allegro. Worcester: 1994.

# Thank you!!



Questions?

Comments?

### **Contact Information**



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